

cont 133  
motors 35 of the respective actuators 9a by means of the wiring 40. The reaching of one of the positions for the engagement of a transmission ratio by the lever L thus results in the engagement of the corresponding gear ratio of the gearbox C by means of the actuators in the control unit 9

**IN THE DRAWINGS:**

A copy of a proposed substitute figure 1 is submitted herewith for approval.

**IN THE CLAIMS:**

Please enter the following amended claims:

1. (Amended) A unit for servo-assisted operation of a motor-vehicle gearbox (c)  
having a pair of mechanical operating members for selection and engagement, respectively, the combined movement of which brings about the engagement of a selected transmission ratio of the gearbox, the unit comprising actuator means (E) (S) which can control the combined movement of the mechanical operating members in response to the position of remote gearshift means (L) of the gearbox, wherein the actuator means are remote from the gearbox and are connected to the mechanical operating members by means of elongate flexible mechanical transmission elements. (34)

3. (Amended) The operating unit of Claim 2, wherein the actuator means include control means (1) for controlling the movement of the elongate mechanical transmission elements. (1) on gear control unit

4. (Amended) The operating unit of Claim 3, further including an electronic control unit (41) operatively interposed between the control means and sensor means which can detect the instantaneous position of the remote gearshift means of the gearbox, the electronic control unit being arranged to process the signals coming from the sensor means and to send operating signals to the control means in order to bring about the movement of the elongate